

SANYO**LA1140****FM IF System for Car Radio****Overview**

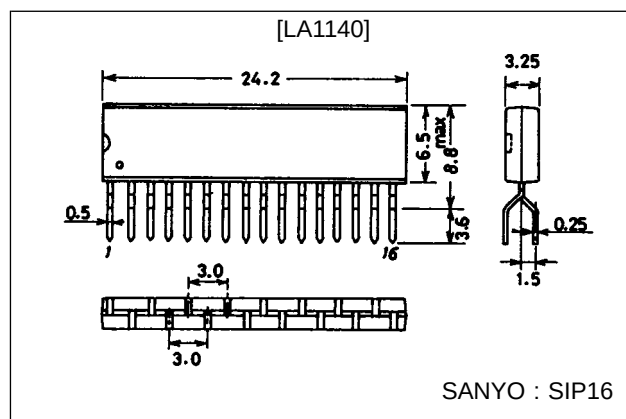
The LA1140 is an IF system IC designed for FM car stereo receivers. It features versatile muting characteristics and allows receiver designers to realize the muting performance according to their design concept. Since the muting characteristics can be varied with a switch or a semi-fixed resistor, DX-Local switching will be accomplished with ease.

Functions

- IF amplification/limiter
- Quadrature detector
- AF preamplifier
- AFC output
- Signal meter output
- AGC output
- Muting bandwidth
- Muting under weak signal strength

Package Dimensions

unit : mm

3020A-SIP16**Features**

- Versatile muting
- a) When muting operation is performed under a weak signal strength, an attenuation slope of the audio output against the input signal strength variations can be set at any given value.
- b) Maximum muting attenuation can be selected to be approximately 6 to 40 dB.
- c) Input signal strength level which actuates the muting circuit can be set freely.
- High limiting sensitivity (25 dB μ typ. with muting off) provides a fine quieting characteristic.
- High S/N (78 dB typ.)
- Low distortion (0.05% typ.) available if used with double-tuned circuits.
- Good AMR (63 dB typ. with 6 stages of differential IF amplifiers).
- Signal meter drive output proportional to the input signal strength in dB (suitable to control multiplex IC LA3370).
- Clamped ($\pm V_{BE}$) AFC output, bandwidth adjustable.
- Delayed AGC output for front end circuit.
- Small space factor due to single-ended package employed.
- 3 mm pitch of pin terminals permitting ease-to-write PC board pattern.

Specifications

Maximum Ratings at $T_a = 25^\circ\text{C}$

Parameter	Symbol	Conditions	Ratings	Unit
Maximum supply voltage	V_{CC} max	Pin 12	16	V
Maximum supply current	I_{CC} max	Pin 12	40	mA
Allowable power dissipation	P_d max	$T_a = 25^\circ\text{C}$	640	mW
		$T_a = 70^\circ\text{C}$	460	mW
Input voltage	V_{IN}	Pin 1 to 2	± 1	Vp-p
Flow-in current	I_2	Pin 2	± 0.2	mA
	I_3	Pin 3	± 0.2	mA
	I_6	Pin 6	2	mA
Flow-out current	I_5	Pin 5	1	mA
	I_{13}	Pin 13	2	mA
	I_{14}	Pin 14	2	mA
	I_{15}	Pin 15	1	mA
	I_{16}	Pin 16	1	mA
Operating temperature	T_{opr}		-20 to $+70$	$^\circ\text{C}$
Storage temperature	T_{stg}		-40 to $+125$	$^\circ\text{C}$

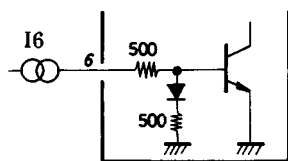
Operating Conditions at $T_a = 25^\circ\text{C}$

Parameter	Symbol	Conditions	Ratings	Unit
Recommended supply voltage	V_{CC}		8	V
Operating voltage range	V_{CC} op		7.5 to 16	V

Operating Characteristics at $T_a = 25^\circ\text{C}$, $V_{CC} = 8$ V, $f = 10.7$ MHz, See specified Test Circuit

Parameter	Symbol	Conditions	min	typ	max	Unit
Quiescent current	I_{CCO}	Quiescent	15	21	27	mA
Current drain	I_{CC}	$V_{IN} = 100$ dB μ	20	25	30	mA
Demodulation output	V_O	$V_{IN} = 100$ dB μ , 400 Hz 100% mod.	200	260	320	mVrms
Total harmonic distortion	THD	$V_{IN} = 100$ dB μ , 400 Hz 100% mod.		0.05	0.2	%
Signal-to-noise ratio	S/N	$V_{IN} = 100$ dB μ , 400 Hz 100% mod.	72	78		dB
Input limiting voltage	V_{IN} (lim)	V_O : 3 dB down, 400 Hz 100% mod.		25	29	dB μ
Muting sensitivity	V_{IN} (Mute)	$V_{14} = 2.0$ V	22	26	32	dB μ
Muting attenuation (1)	Mute (A_{CC})	$V_6 = 2.0$ V (22 k Ω), $V_{IN} = 100$ dB μ , 400 Hz 100% mod.	10	15	20	dB
Muting attenuation (2)	Mute (A_{CC})	$V_6 = 5.0$ V (22 k Ω), $V_{IN} = 100$ dB μ , 400 Hz 100% mod.	24	28	32	dB
Muting bandwidth	BW (Mute)	$V_{IN} = 100$ dB μ , $V_{14} = 2.0$ V	140	210	370	kHz
AM rejection ratio	AMR	$V_{IN} = 100$ dB μ , FM 400 Hz 100% mod., AM 1 kHz 30% mod.	50	63		dB
Muting drive output	V_{14-0}	Quiescent	3.5	4.2	5.0	V
Muting drive output	V_{14-100}	$V_{IN} = 100$ dB μ	0	0	0.3	V
Signal meter output (1)	V_{15-0}	Quiescent	0	0.1	0.3	V
Signal meter output (2)	V_{15-50}	$V_{IN} = 50$ dB μ	0.8	1.4	2.0	V
Signal meter output (3)	V_{15-70}	$V_{IN} = 70$ dB μ	1.6	2.4	3.2	V
Signal meter output (4)	V_{15-100}	$V_{IN} = 100$ dB μ	4.5	5.3	6.0	V
AGC output (1)	V_{16-0}	Quiescent	3.5	4.1	4.5	V
AGC output (2)	V_{16-100}	$V_{IN} = 100$ dB μ	0	0.02	0.3	V
Offset voltage (1)	V_{7-13}	Quiescent, pin 7 to 13	-0.25	0	$+0.25$	V
Offset voltage (2)	V_{8-13}	Quiescent, pin 8 to 13	-0.5	0	$+0.5$	V

Since the muting control input pin 6 is connected to the base of the emitter grounded transistor (through a protection resistor of $500\ \Omega$ in series), the voltage between pin 6 and GND is about 0.6 V when the control current is applied. In actual cases, the muting operation is accomplished by applying a voltage drive type muting drive output (pin 14 to pin 6 through a high resistance (up to $20\ \text{k}\Omega$)).



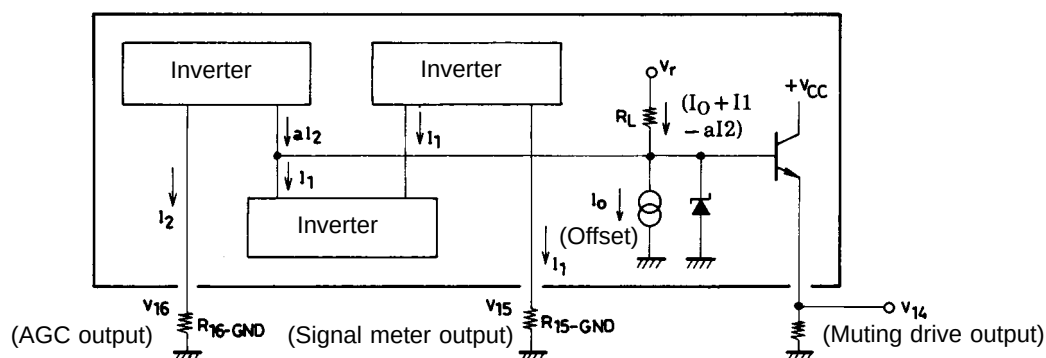
Unit (resistance: Ω)

The muting drive output comes in three types:

- 1) Hole detector output which develops a voltage when C/N (carrier-to-noise ratio) lowers under weak signal input conditions.
- 2) A reversed output of the signal strength indicating output (output at pin 15)
- 3) A bandwidth limited muting drive output which develops a voltage when the AFC output becomes higher than $\pm V_{BE}$ during tuning-off operation.

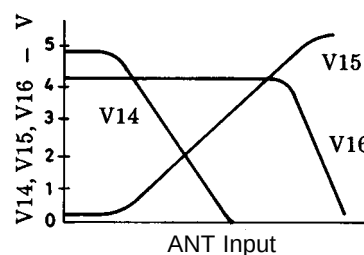
All these outputs are led to an OR circuit and the processed output is developed at pin 14. Of the above muting drive outputs, descriptions on the hole detector output and the bandwidth limited muting drive output will be omitted, since they are the same as those used in conventional quadrature detector ICs (such as LA1230, LA1231N).

The inverted output of the signal strength indication output is obtained as illustrated below.

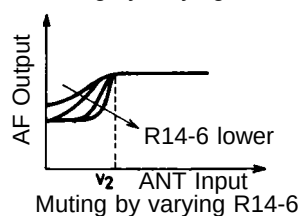
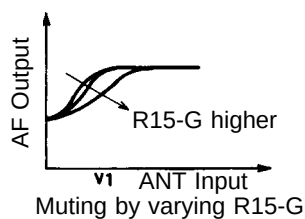


By referring to the illustration, V_{14} is given by the formula: $V_{14} = V_r - (I_O + I_1 - aI_2)R_L - V_{BE}$.

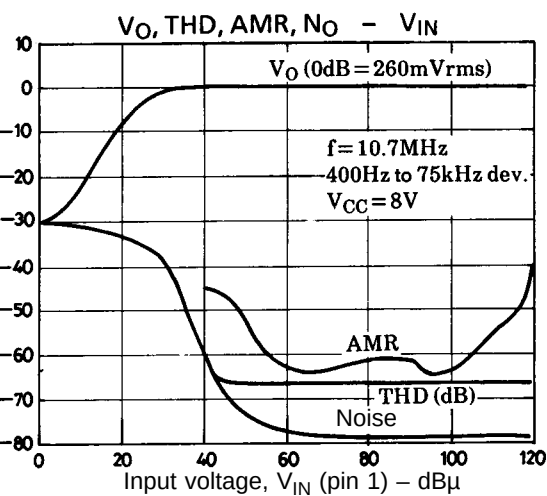
Conditions are: $V_r \cong 4.9\ \text{V}$, $I_O \cong 0.2\ \text{mA}$, $a \cong 2$, $R_L = 22\ \text{k}\Omega$, $V_{BE} \cong 0.6\ \text{V}$, $I_1 = V_{15}/R_{15-G}$, $I_2 = V_{16}/R_{16-G}$ where V_{16} is a constant equal to 4.1 V (typ) for medium or lower signal input levels, where the muting drive output is required. Since the V_{15} increases proportionally to the increase of the input signal strength, I_1 will also increase. Therefore the V_{14} will decrease with increasing signal strength. Thus the required muting drive output can be obtained by selecting proper values of R_{15-G} and R_{16-G} . For example, the muting drive output moves toward strong input signal level if the R_{16-G} is decreased, or the muting drive output becomes zero due to the offset current I_O under a weak signal input condition, if the R_{16-G} is increased to infinity (namely pin 16 is opened). However the muting drive output caused by a whole detector still exists in this case. Increasing R_{15-G} decreases the slope of the curve for the muting drive output vs. antenna signal input level, or decreasing the R_{15-G} increases the slope of the curve. Furthermore, varying the value of a resistor connected between the muting drive output (pin 14) and the muting control input (pin 6) changes the value of the muting control current required to obtain the same muting drive output, accordingly the slope of the curve for muting attenuation vs. antenna signal input level is also changed. These characteristics investigated by using an actual receiver are shown on the curves below.



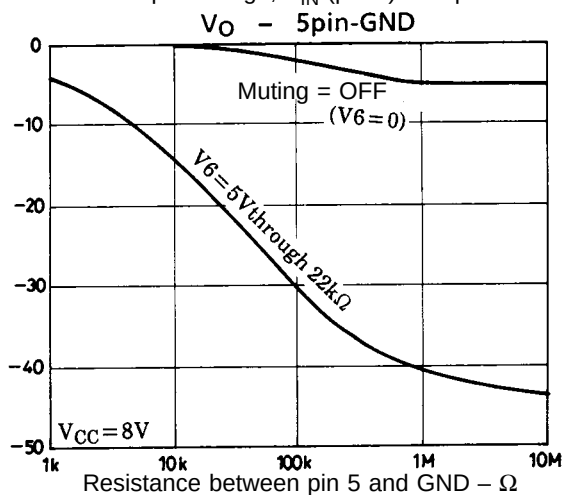
The general method to adjust the muting circuit of the LA1140 is: to set the signal input level required to actuate the muting circuit with the R_{16-G} , to adjust the slope of the curve for the muting attenuation vs. antenna signal input with the R_{15-G} , and to adjust the maximum muting attenuation (determined by setting the noise level at no signal) with the R_{5-G} . The slope of the curve for the muting attenuation vs. antenna signal input level can also be adjusted by the resistor connected between pins 14 and 6 in addition to R_{15-G} , however, selecting a resistor too high does not allow the muting control current flowing into pin 6 to reach $120\ \mu\text{A}$ even through the maximum muting drive output (V_{14}) is applied, namely the muting attenuation does not reach its maximum value. Accordingly a recommended value of the resistor between pins 14 and 6 is about $22\ \text{k}\Omega$.



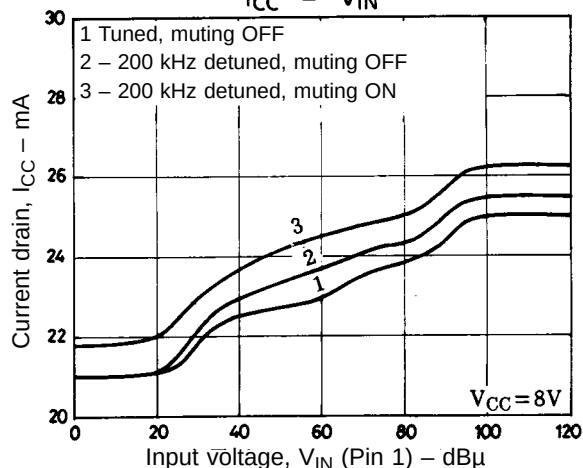
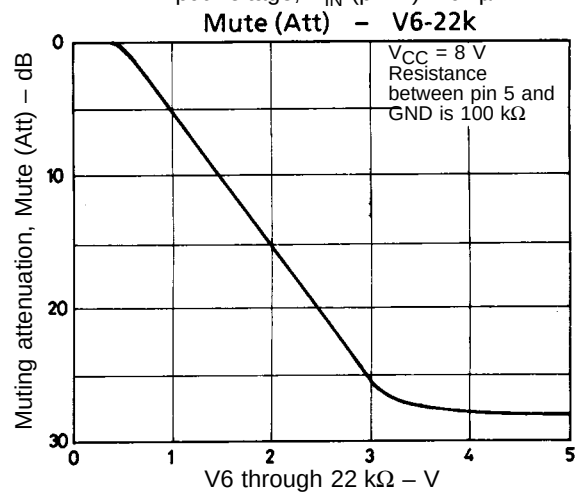
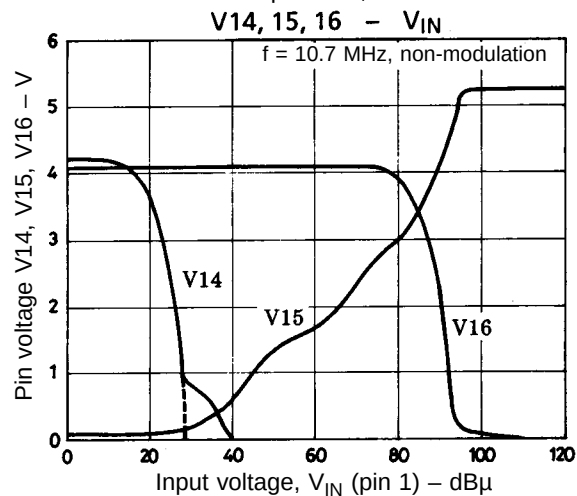
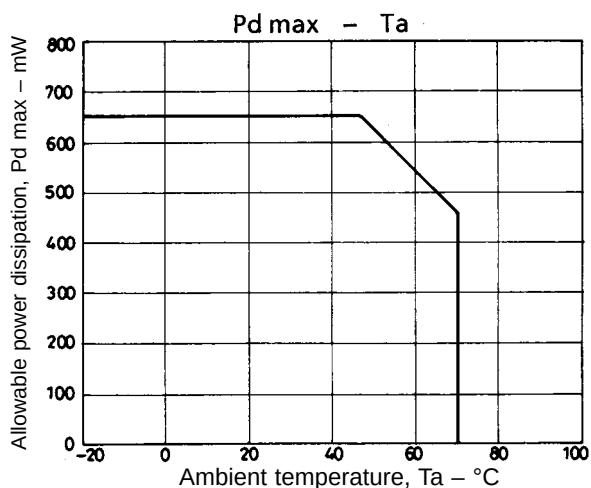
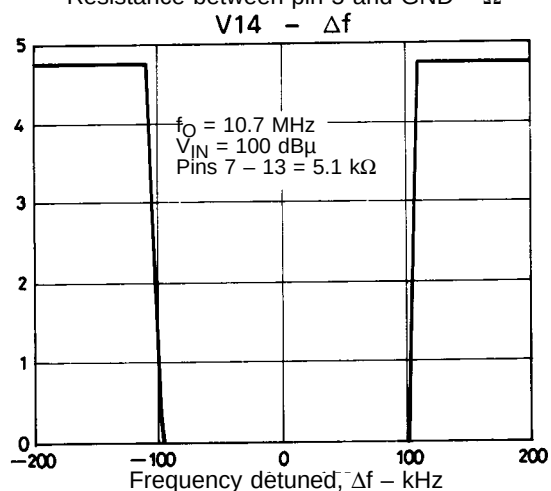
Demodulation output V_O , distortion THD, Noise
AM rejection AMR, Noise N_O

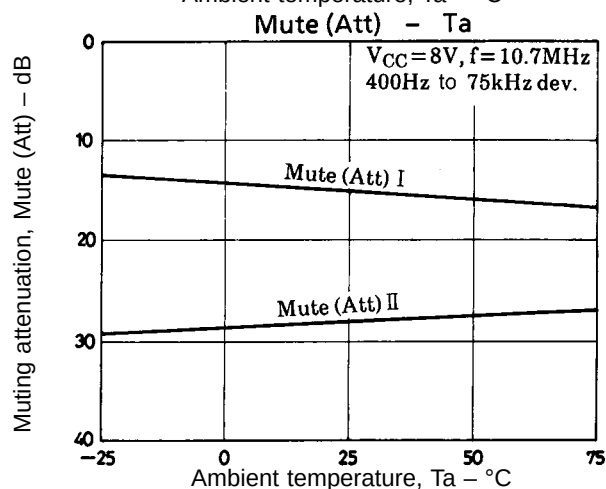
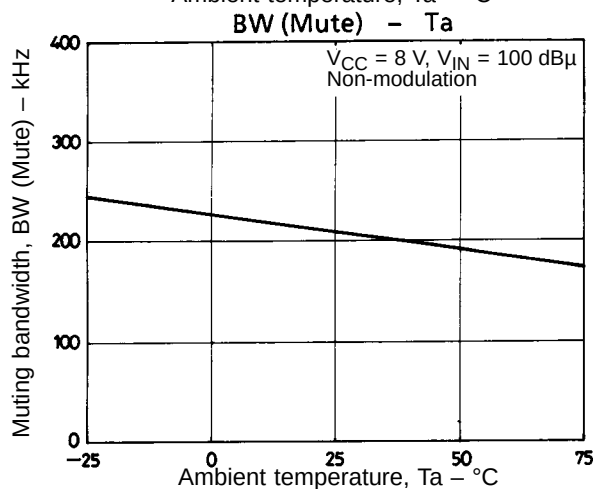
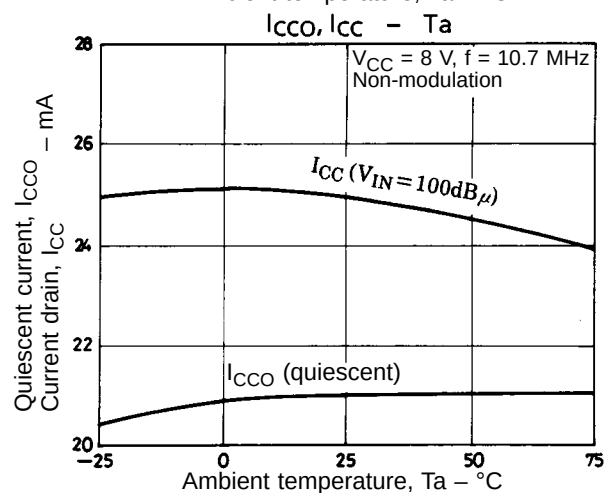
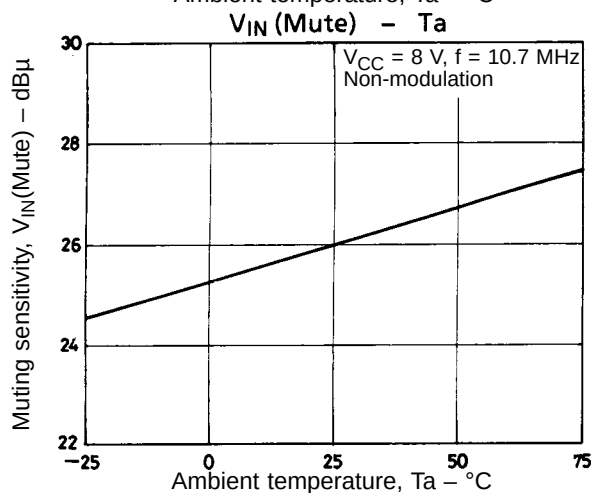
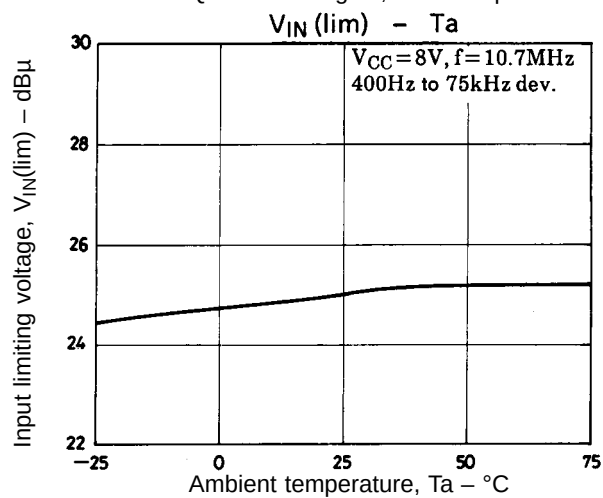
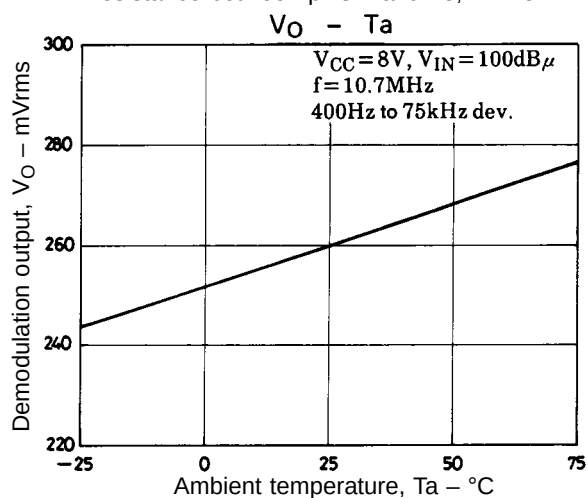
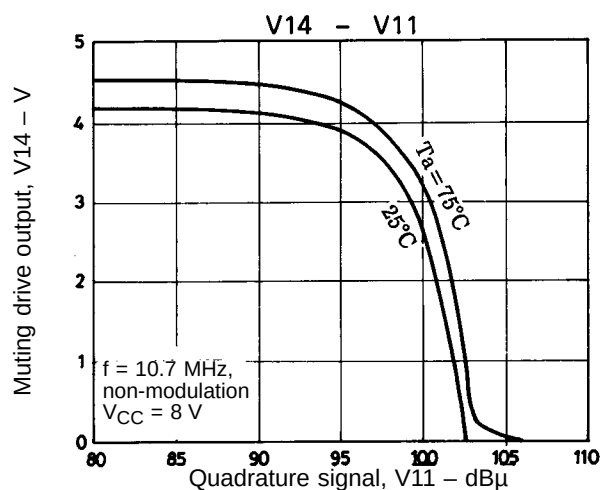
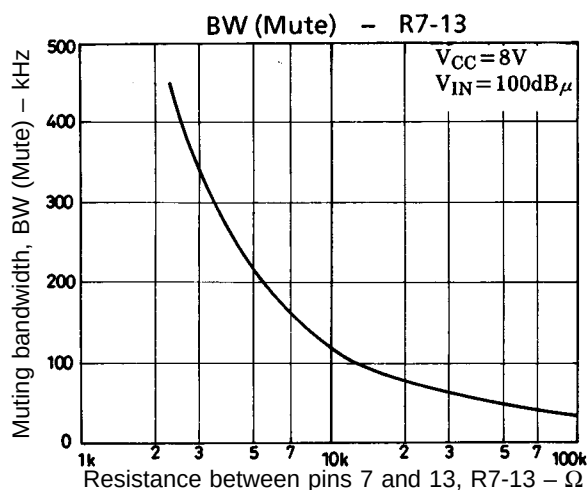


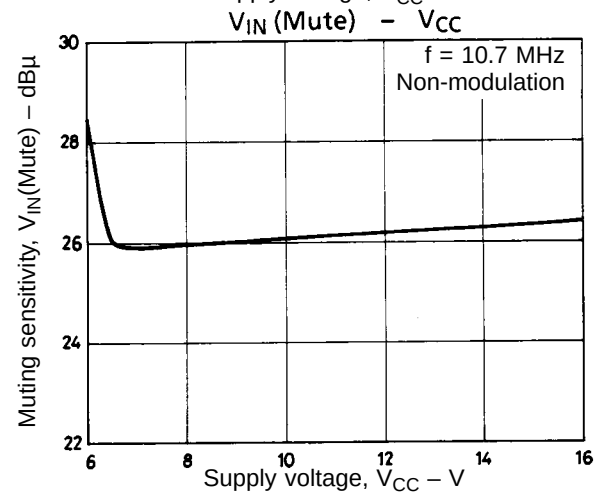
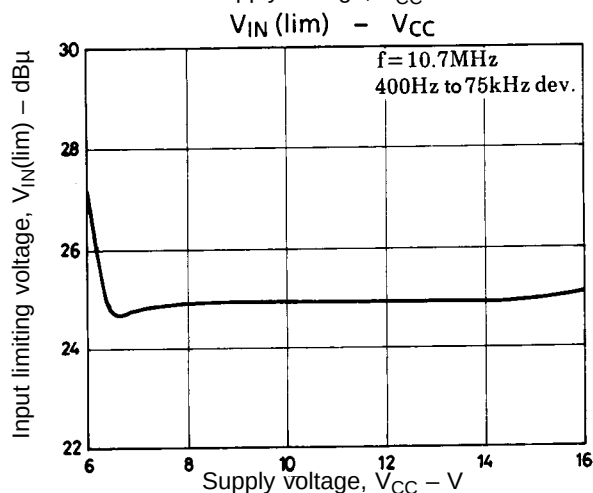
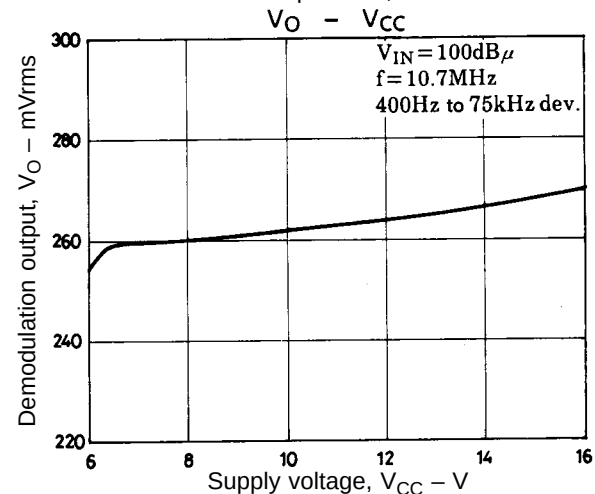
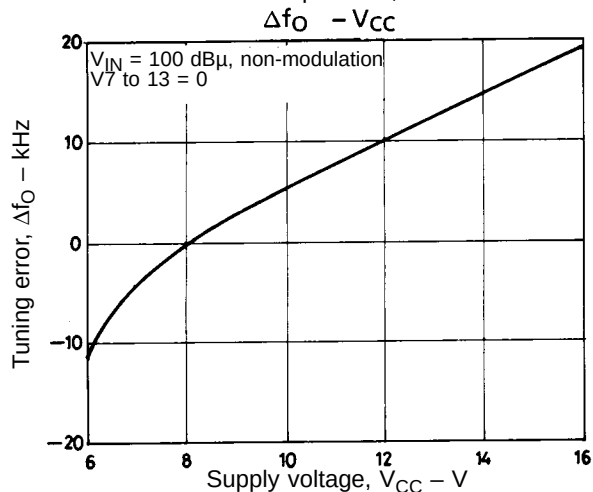
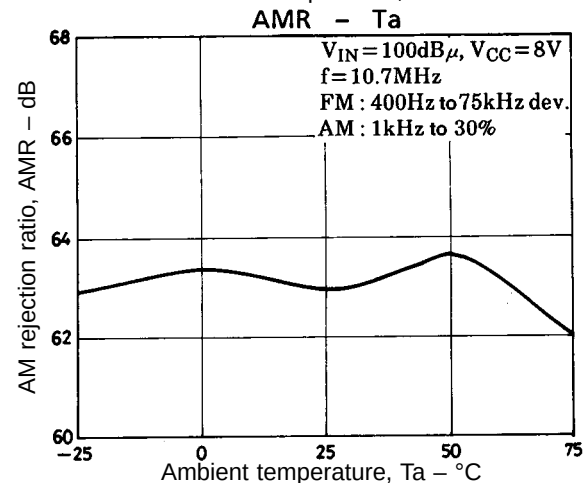
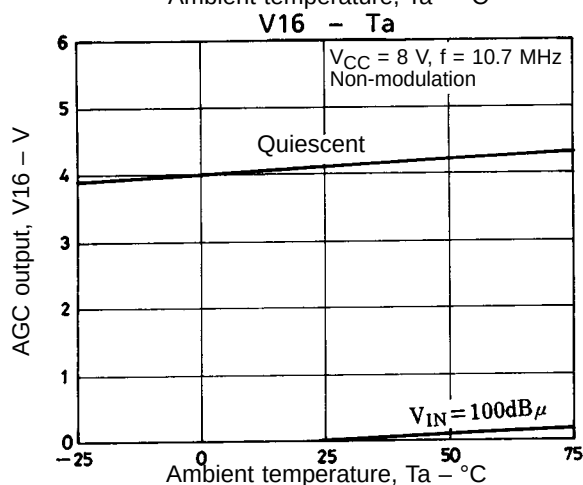
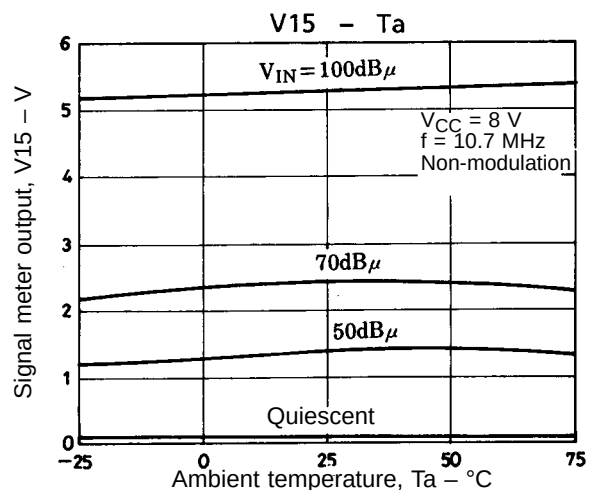
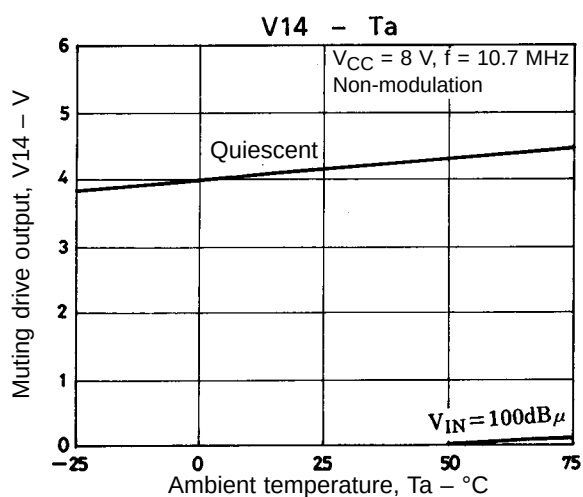
Demodulation output, V_O - dB

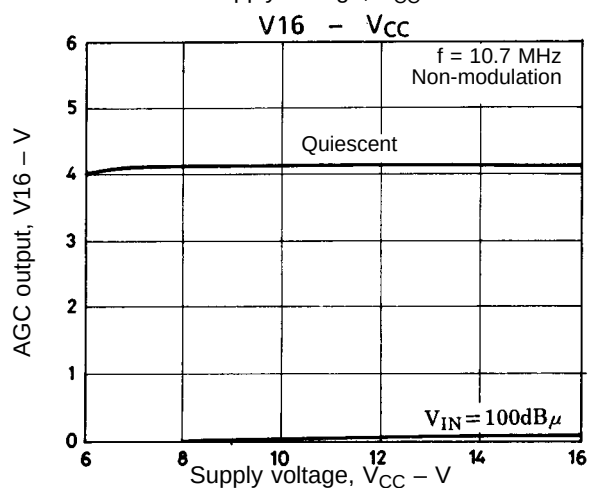
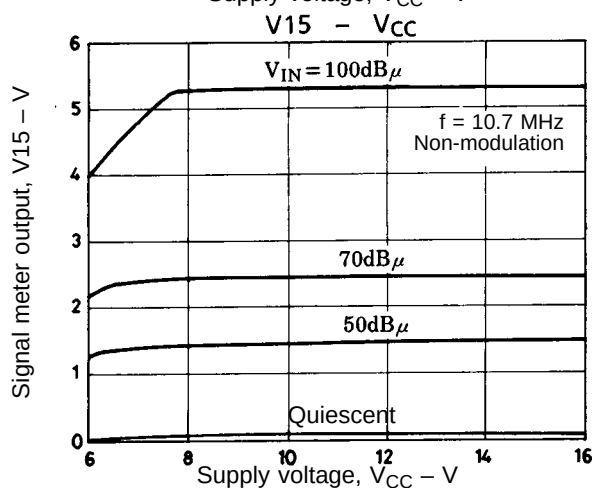
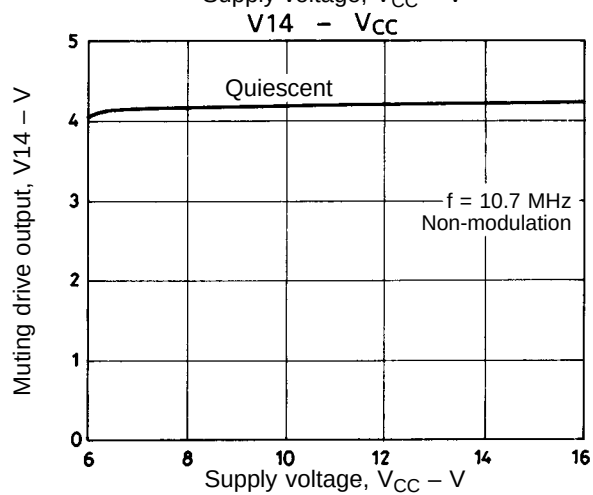
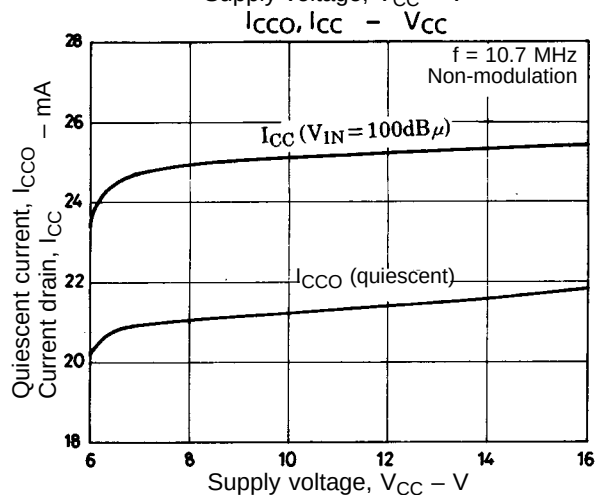
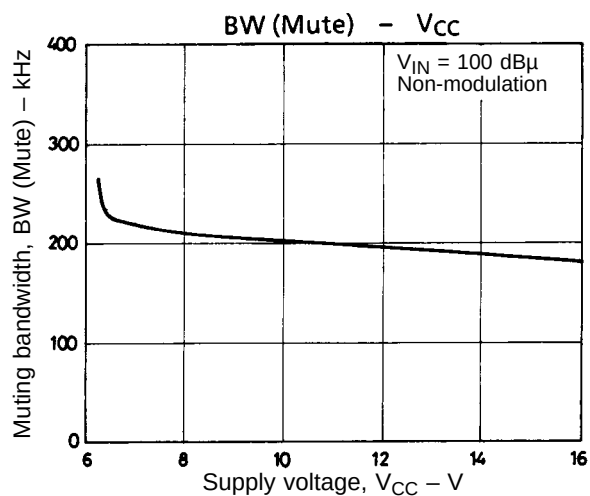
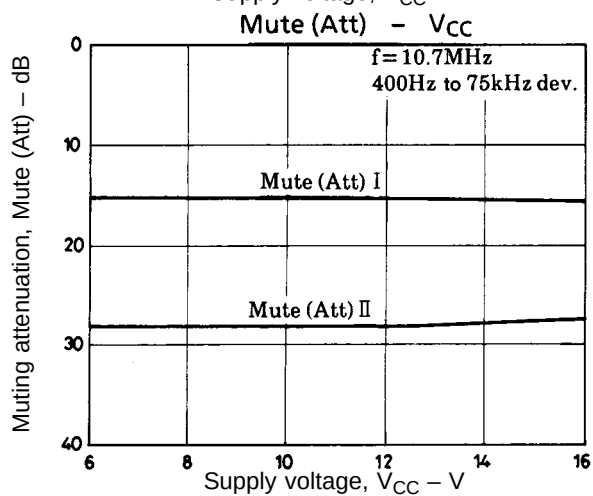
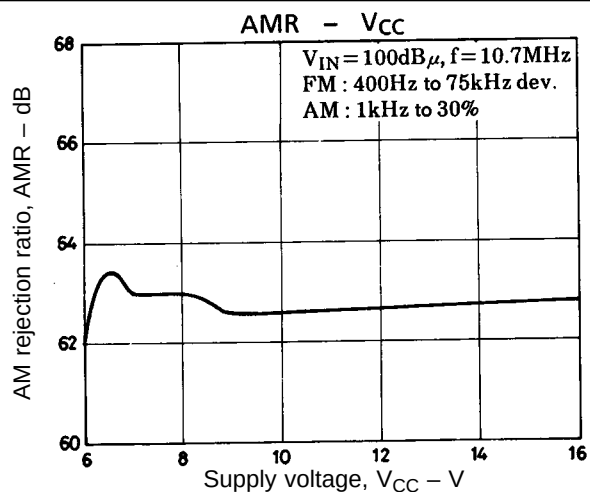
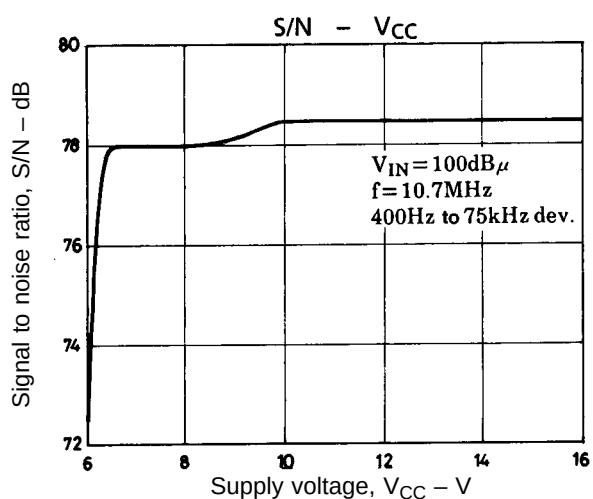


Bandwidth muting drive output, V_{14} - V





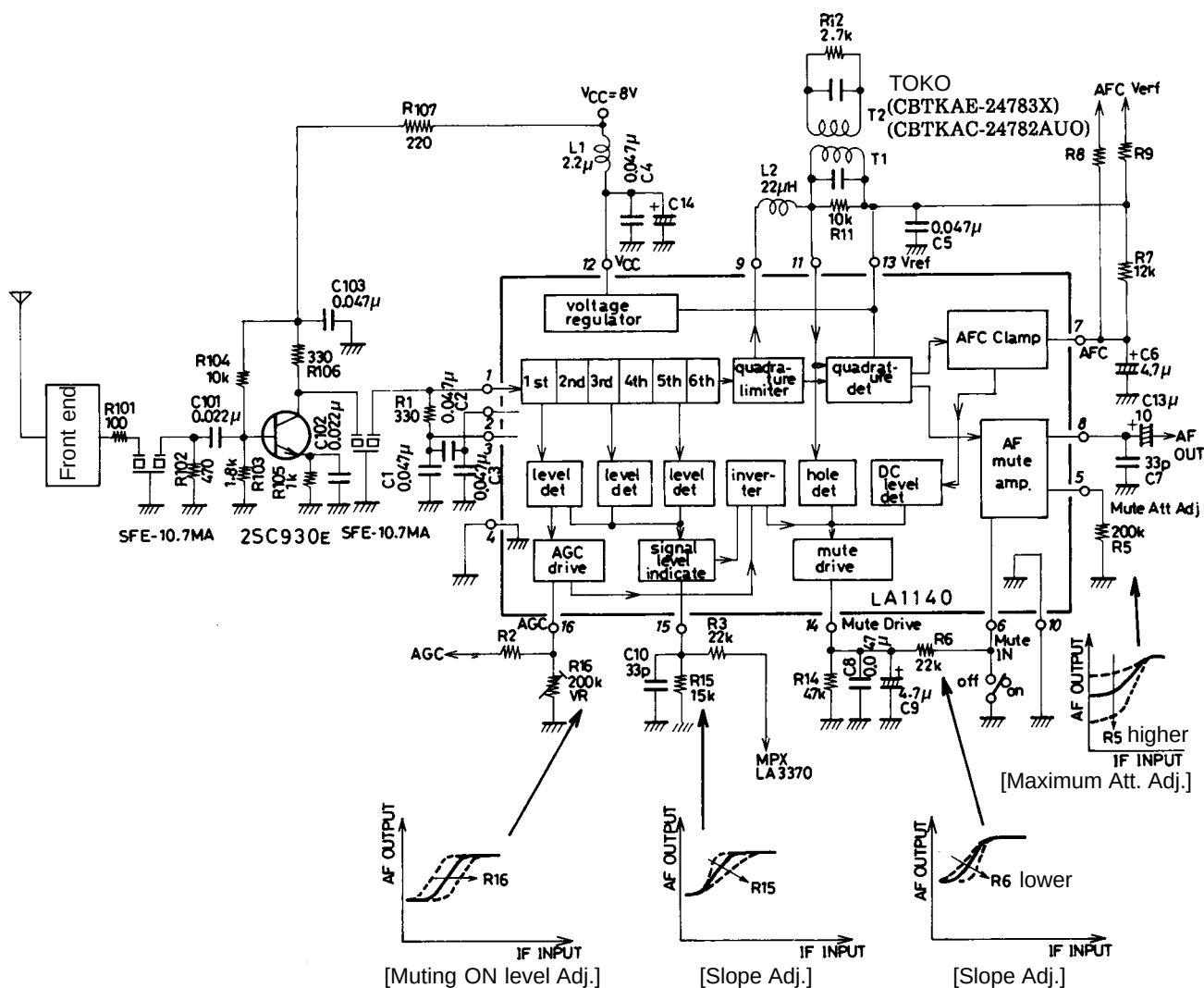




Proper cares in using LA1140

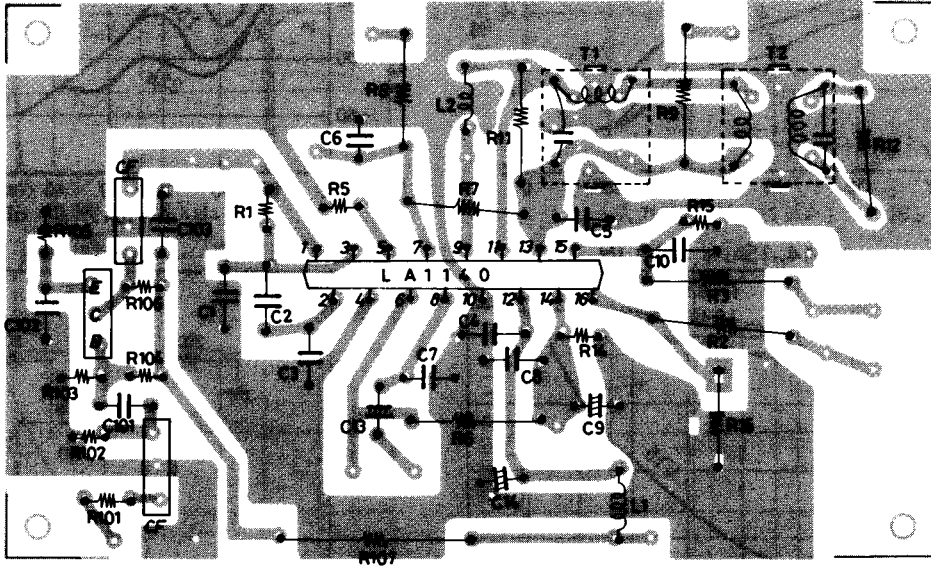
- 1) The detector transformers should be designed to develop a quadrature signal (pin 11) of higher than 175 mVrms (approximately 105 dB μ) under high antenna signal input. If the quadrature signal strength is less than 125 mVrms, the muting drive output (V14) cannot decrease to zero even in a strong signal strength. Furthermore, when the quadrature signal strength lies between 125 mV and 175 mV, the muting drive output may move from zero to plus under high temperature conditions.
- 2) When designing a PC board, special care should be given to the ground pattern layout by referring to that of the recommend PC board example as shown below.
- 3) Do not connect a capacitor directly between pin 16 and ground. If the signal intensity of IF input varies in the vicinity of 90 dB μ , the voltage at pin 16 varies. Thus, charging/discharging current flows into the capacitor and goes to the muting drive output (pin 14) through the inverter inside the IC, thereby causing the muting to malfunction.

Sample Application Circuit 1

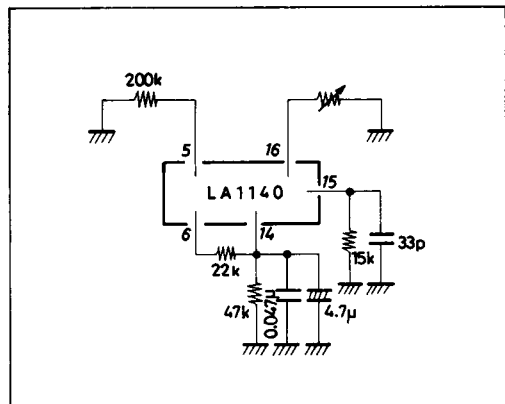
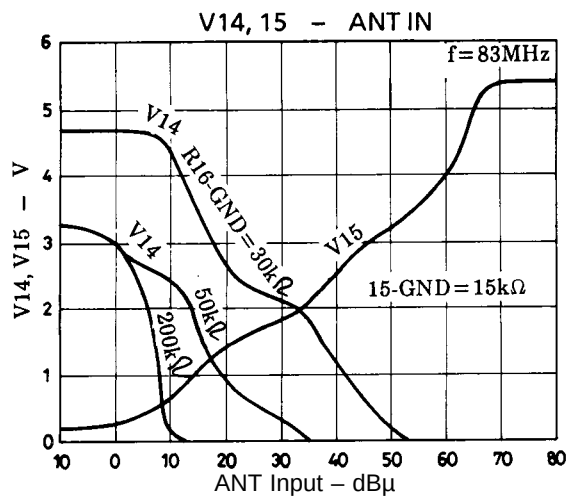
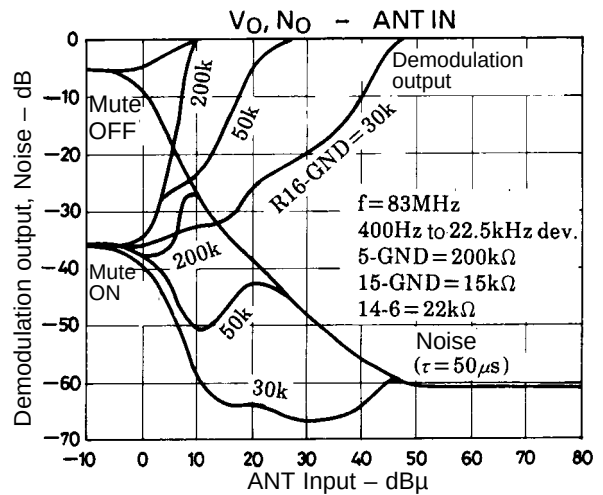


Unit (resistance: Ω , capacitance: F)

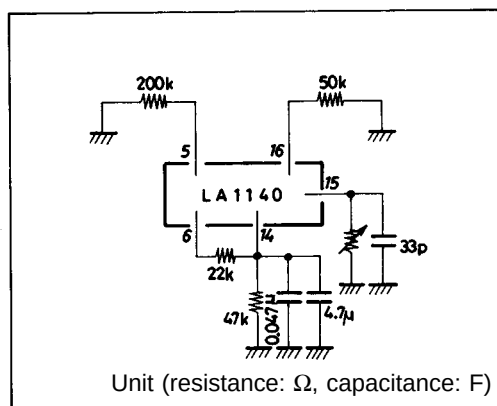
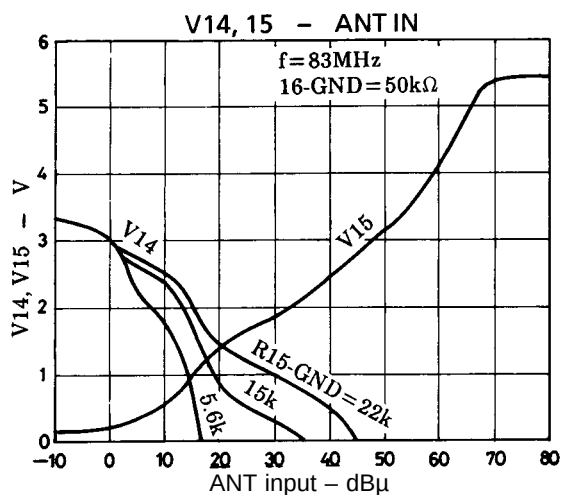
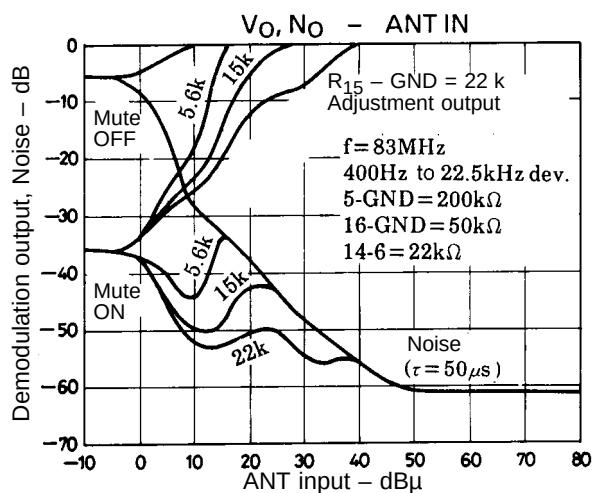
Sample Printed Circuit Pattern

(Cu-foiled side $45 \times 75 \text{ mm}^2$)

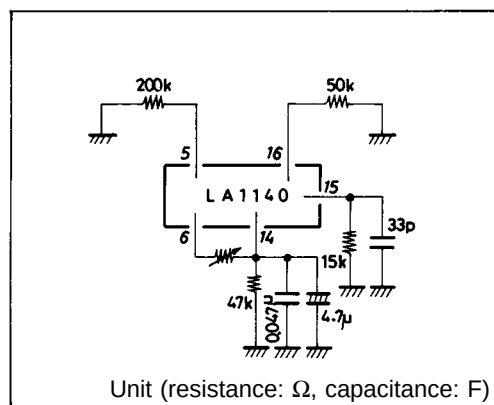
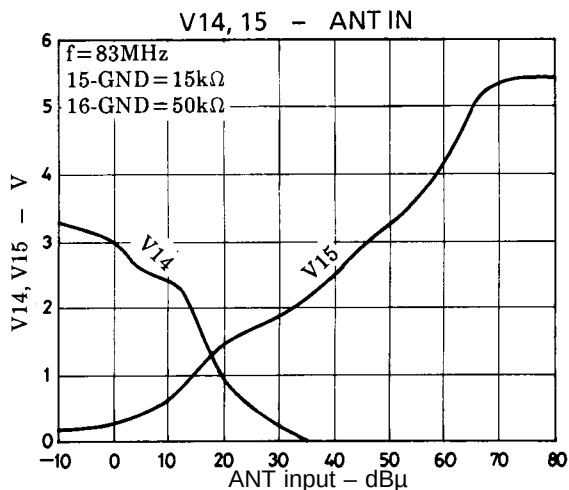
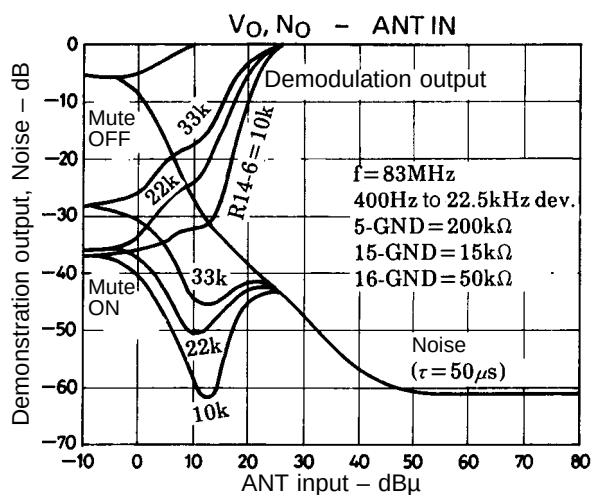
- Variations of muting characteristics with a resistor connected between pin 16 and GND varied. (Muting threshold level adjustment)



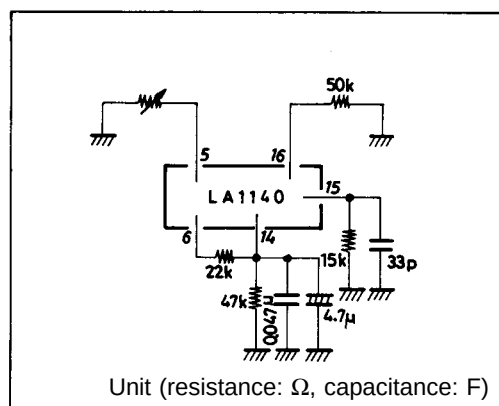
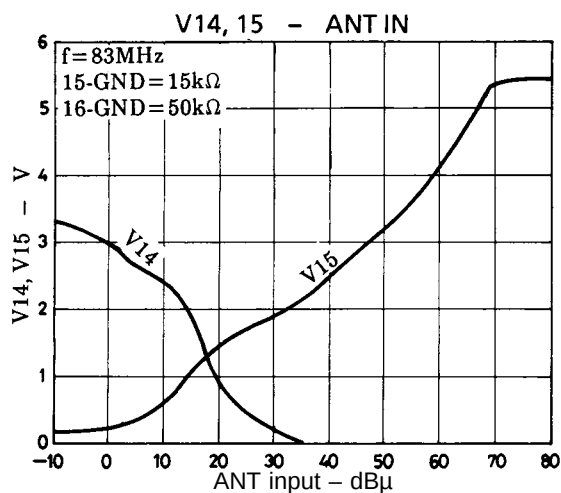
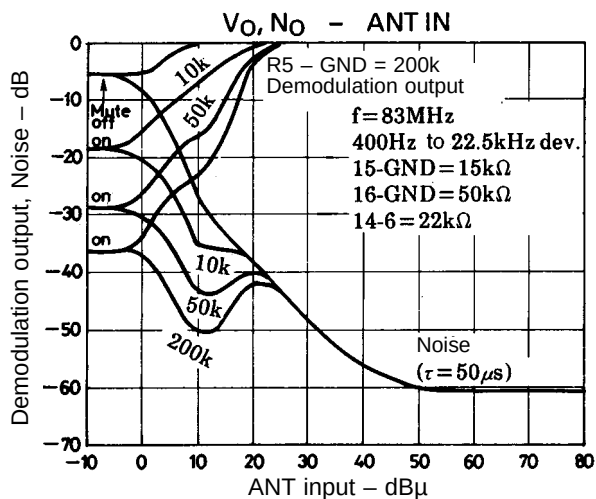
- Variation of muting characteristics with a resistor connected between pin 15 and GND varied.
(Slope adjustment 1 of the curve for muting attenuation vs. antenna signal input level)



- Variations of muting characteristics with a resistor connected between pins 14 and 6 varied.
(Slope adjustment 2 of the curve for muting attenuation vs. antenna signal input level)



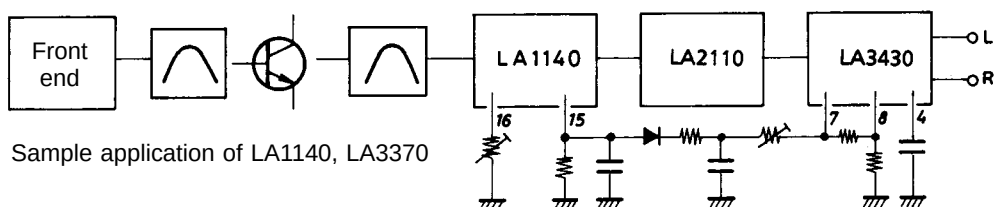
- Variations of muting characteristics with a resistor connected between pin 5 and GND varied.
(Adjustment of the maximum muting attenuation)



Sample Application Circuit 2

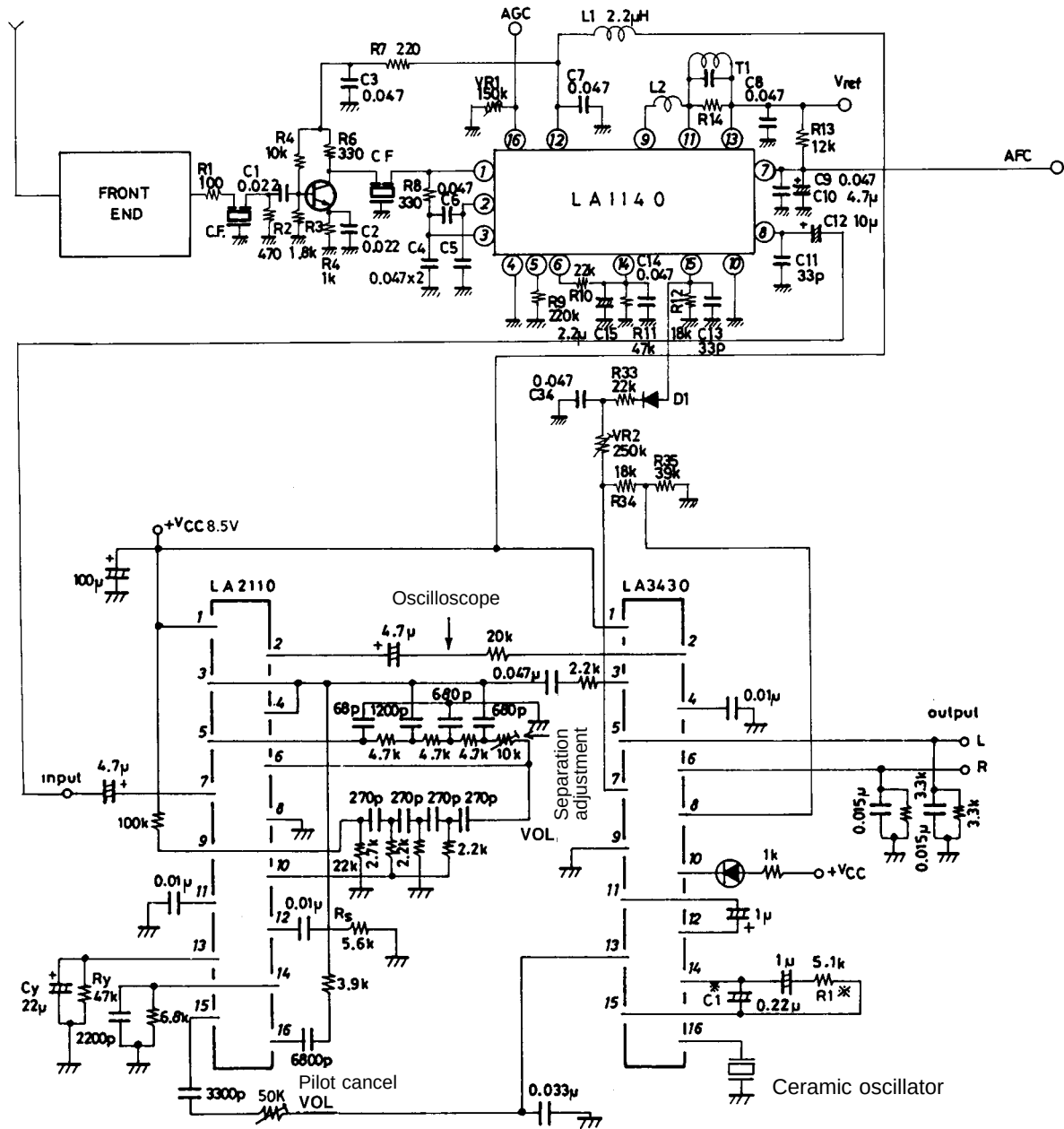
High Frequency Section of Car Radio and Car Stereo with Noise Canceller and FM Stereo Multiplexer

Almost all noise under a medium and lower input signal strength can be rejected by processing the muting characteristic of the LA1140, the stereo noise control (SNC) characteristic and the high cut control characteristic of the LA3370. These examples are as follows:

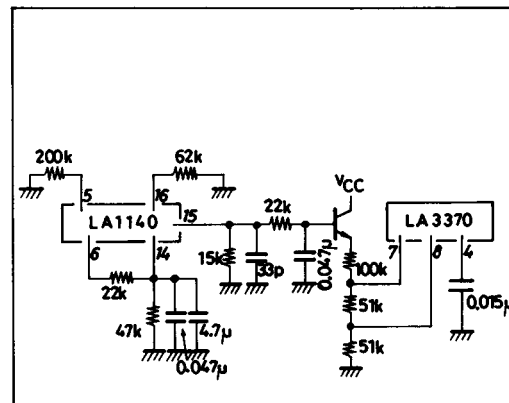
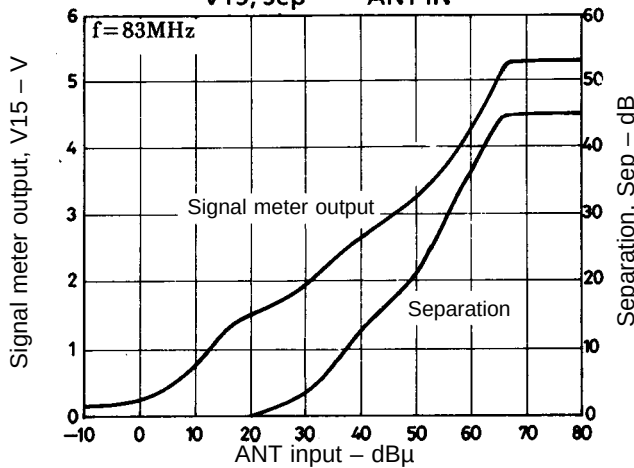
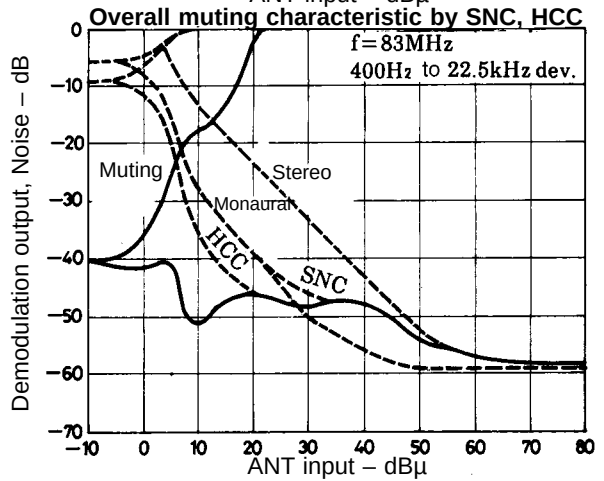
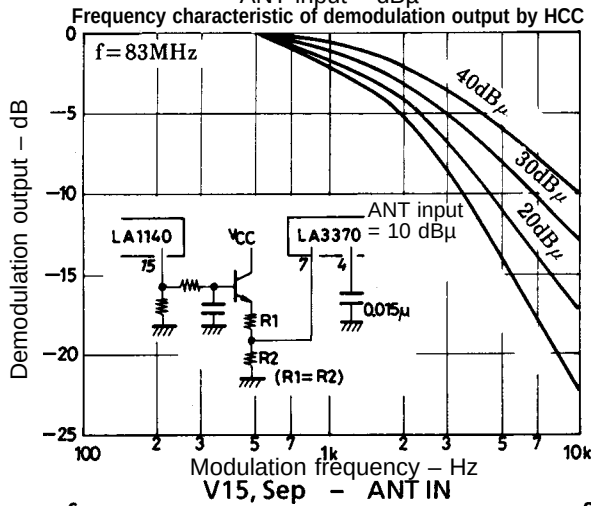
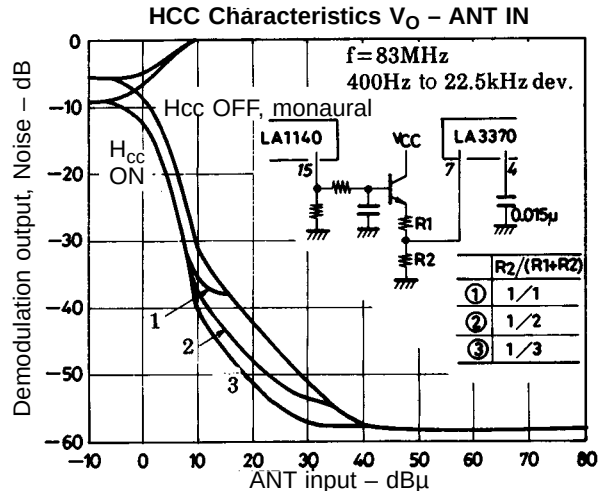
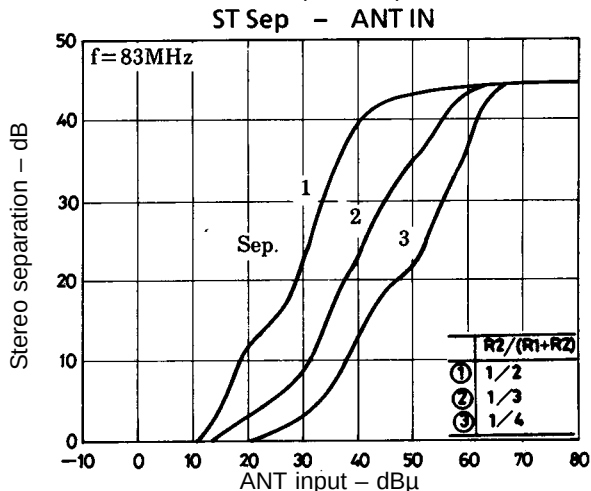
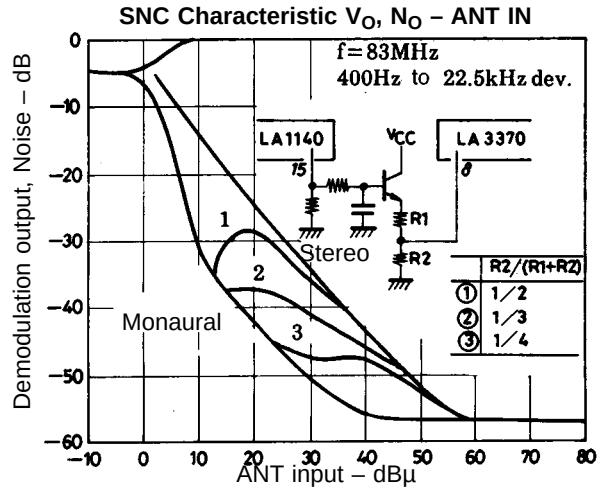
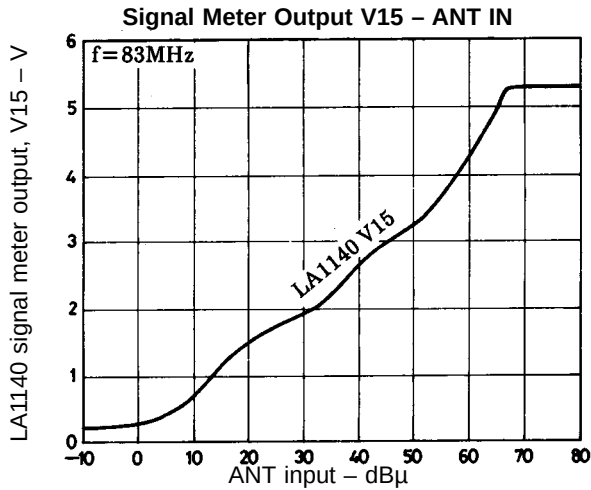


LA1140

Circuit Diagram



Unit (resistance: Ω , capacitance: F)



LA1140

Item	Manufacturer	Type Number	Package	Fixed Inductor	Damping Resistor	Note
Double tuning	Toko	Pri. CBTAC-24782AUO Sec. CBTAE-24783X	10 mm sq. 10 mm sq.	22 μ H	10 k Ω 2.7 k Ω	
	Sumida	Pri. 0232-702-066 Sec. 0232-702-067	7 mm sq. 7 mm sq.	22 μ H	10 k Ω 2.7 k Ω	
Single tuning	Toko	119AC-14086Z MTKAC-25639Z	7 mm sq. 10 mm sq.	22 μ H 22 μ H	10 k Ω 10 k Ω	
	Korin	57-1011-01 59-1167-04	7 mm sq. 10 mm sq.	22 μ H (22 μ H*)	22 k Ω 5.6 k Ω	*:Included
	Sumida	24M-190-268 24M-190-267	7 mm sq. 10 mm sq.	22 μ H 22 μ H	5.6 k Ω 5.6 k Ω	
	Sankyo	DC-11	7 mm sq.	(22 μ H*)	10 k Ω	*:Included

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